

Application of fully automated centralized voltage regulation in transmission system operation management

Renata Rubeša, Marko Rekić, Zoran Bunčec, Tomislav Stupić

Summary — The influence of wind farms, inclusion of distributed energy and the energy market has a large impact on the voltage profile in a transmission system. The Croatian Transmission System Operator HOPS has implemented VVC (Volt Var Control) system which was one of the subprojects included in the EU co-founded Sincro. Grid smart grid project that was financed by the EU CEF fund. The main goal of the project is to raise voltage quality in the transmission network. VVC system is an optimal power flow-based application which calculates the optimal solution regarding the desired objective function, available control variables and a defined set of constraints. To achieve the calculated optimal power system state, control of field devices is included in the process of optimization by shifting tap changer positions or changing setpoint values of reactive power injection. Voltage and reactive power constraints are set accordingly to available regulating devices included in the optimization. The lack of automatic coordination of reactive power resources motivated this work for implementing an advanced VVC for real time control of reactive power in partially automatic and fully automatic (closed loop) mode using the optimal power flow (OPF) algorithm. Due to its complexity, the closed loop approach of reactive power regulation is rarely used in the TSO community and the HOPS is one of the first TSOs that implemented regulation in such manner. Except fully automatic mode of operation, VVC can be used in semi-auto or manual mode. For a successful implementation several safety algorithms are implemented to avoid many unwanted situations in the power system such as voltage breakdown, overloading of regulating equipment and similar.

Keywords — Volt Var Control – Optimization - Transmission Network - Optimal Power Flow - Voltage Profile

I. INTRODUCTION

Transmission System Operators are responsible for the security of operation, facilitation of regional markets and integration of renewable energy sources (RES). Thus, development of grid infrastructure, supporting technologies and mechanisms are key elements for proper and timely integration of RES. In recent years, the Croatian power system has been increasingly challenged by contradictory influences impacting the operation of the power systems:

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- Support of RES integration to meet the EU targets,
- A lower electricity consumption due to the economic crisis,
- A growing lack of centralized electricity production for electric system support,
- The high interconnectivity between the neighboring control zones.

Consequently, the Croatian transmission System Operator HOPS observes growing issues in keeping the voltage profile of the transmission network inside the prescribed limits. This issue has been addressed by implementing a power system voltage and reactive power regulation scheme on a national level which would allow more RES generation to be connected to the transmission and distribution power systems. Power system voltage and reactive power regulation schemes can be generally classified as hierarchical or as centralized voltage regulation systems. Ways of implementing these two regulation systems vary greatly from one TSO to another [1]. Hierarchical regulation rests on implementation of three temporally and spatially separated control levels: primary, secondary, and tertiary control [2]. Primary voltage regulation automatically implies response of local voltage regulators, primarily synchronous generators and on-load tap changers in substations. Secondary regulation refers to voltage regulation within a defined zone, while tertiary regulation is carried out on regional or national level. The problem is usually seen as a static problem, whose solution is identical to an open-loop optimization based volt/var management [3]. In HOPS the implemented voltage and reactive power regulation scheme, referred to as tertiary control on a national level and is based on an optimal power flow (OPF) type algorithm. Addressing the issue of implementing such a complex system in a closed loop operation in a TSO led to several open questions:

- The definition of voltage optimality accompanied with regional contributions for a system wide performance criterion.
- Improvement of voltage profile in particular regions experiencing shortage of voltage support [3].
- Voltage profile and stability is mainly a local issue, but some of major large network disturbances and blackouts were caused by voltage stability issues. Apply the automatic operation of the voltage and reactive power regulation scheme ensuring safe and reliable network operation.

This paper will elaborate on these questions and how they were practically solved in HOPS in scope of Sincro.Grid VVC project.

II. VOLT VAR CONTROL SYSTEM DESIGN

A. PRIMARY AND TERTIARY REGULATION SCHEME

Most transformers (220/110 kV and 400/110 kV transformers) are equipped with an onload tap changer (OLTC) that can change the ratio of the transformation in operation and thus control the voltage on the regulated side of the transformer. Local voltage regulators on transformers typically regulate the lower voltage side of transformers.

Unlike local voltage regulators, the central Volt and Var Control (VVC) system has insight into the entire network and the ability to manage voltages throughout the power network. The calculation of the optimal power flows of the central optimizer is defined by the objective function and the set voltage limits. The objective function of the VVC system is set to minimize the operating losses in the system [4]. The basic algorithm of the VVC function is the optimization algorithm of the OPF function based on the interior point method. The execution of the VVC output (is executed by the SCADA/EMS system installed in HOPS). The ability to manage voltages in the power network largely depends on the available objects in the optimization. In the case of VVC systems in HOPS, it is possible to control a total of 28 power transformers and 2 variable shunt reactors (facilities owned by TSO) to which VVC system can issue control orders (with or without the intervention of the dispatcher/operator). Also, 11 production units (5 generators in Hydro Power Plants, 3 generators in Thermal Power Plants and 4 generators in Wind Power Plants) are included in the optimization calculation. For the VVC calculation to be successful and the control orders ready to be issued to the facilities, the optimal results of all voltage values must be within the defined limits. Therefore, it is very important, depending on the involvement of objects in the optimization, to define voltage limits for individual nodes and analyze the voltage sensitivity of individual objects included in the optimization to avoid large movement of individual objects in optimization.

TABLE I

COMPARISON OF LOCAL VOLTAGE REGULATORS AND CENTRAL VOLTAGE AND REACTIVE POWER REGULATION SCHEME

| | Local voltage regulation | VVC system |
|-------------------|--|---|
| Voltage Control | Voltage control only on the regulated bus | Voltage control of the entire network |
| Regulated bus | Only one regulated bus | All the buses in the network with respect to voltage limits |
| Regulation mode | Automatic maintenance of the selected voltage setpoint value only on the control bus | VVC calculation based on available devices in optimization while meeting the objective function to reduce losses. After the calculation, the set-points can be sent with the approval of the operator/dispatcher or automatically without the confirmation of the operator/dispatcher |
| Loss optimization | Not implemented | Supported, there is insight into voltage conditions throughout the network. After calculating the optimal power flows, the calculation of the difference in losses before and after optimization is visible. |
| Device control | Controls only the OLTC on one object (in case of parallel operation of transformers, mutual communication of regulators on parallel transformers is possible) | Manages selected objects that participate in optimization and have the ability to manage from the VVC system |

B. VVC SYSTEM DESIGN

The VVC system consists of the transmission network model, modelled in the accurate AC manner. The model is imported via the Common Information Model (CIM) standard from the production SCADA/EMS system. The real time measurements and breaker status are imported via IEC 61870-5-104 protocol cyclically with a time interval of one minute [6]. The VVC system runs a state estimation process, and the results are the base case for the OPF process. OPF results (setpoints of control variables) are transferred back from the VVC system to the production SCADA/EMS system via ICCP protocol and dispatched to field devices. The system presented on Figure 1 can be run in semi-automatic mode (the dispatcher sends the controls manually to field devices from the SCADA/EMS system) or in the automatic i.e., closed loop control mode where no dispatcher intervention is needed, and the set points are automatically sent to field devices after each OPF execution. In closed loop control mode, the OPF function can be executed every 15, 30 or 60 minutes.

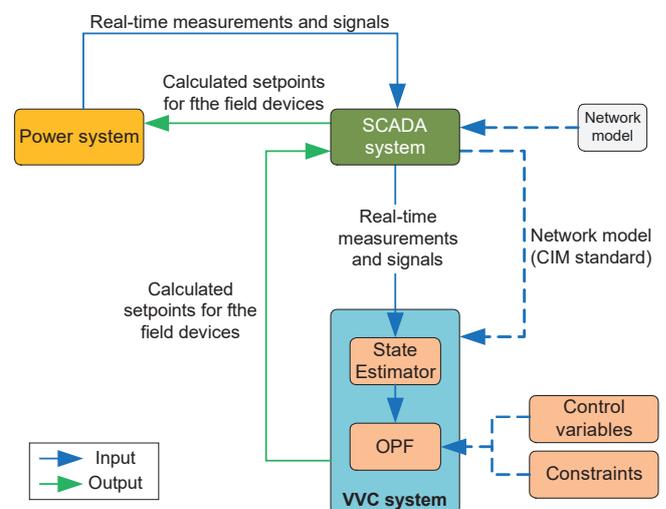


Fig. 1. VVC system design

C. Voltage constraints

Initial voltage low an upper limits or constraints for the 400, 220 and 110 kV voltage levels are defined to be compliant to the COMMISSION REGULATION (EU) 2017/1485 SOGL (System Operation Guidelines) documents and Network Codes. The values of these constraints are defined in Table II. VVC has more rigorous voltage limit compared to the limits from the Network Codes. This provides a safer voltage band within the voltage and can fluctuate due to changes in the network (such as the change of the topology) between two consecutive optimization cycles or runs.

TABLE II

VOLTAGE CONSTRAINTS IN THE VVC SYSTEM

| Voltage level [kV] | Lower limit in VVC [kV] | Upper limit in VVC [kV] | SOGL limits [kV] |
|--------------------|-------------------------|-------------------------|------------------|
| 110 | 105 | 122 | 99 - 123 |
| 220 | 210 | 244 | 198 - 246 |
| 400 | 390 | 418 | 360 - 420 |

Figure 2 below shows the graphical representation of 220 kV node voltages in one region of the transmission network, during a 4-day time span when VVC performed the optimization cycles (left side) and the equally long period without reactive power optimization (right side). In the period without optimization (right side) of the figure only local (primary) voltage regulation was active.

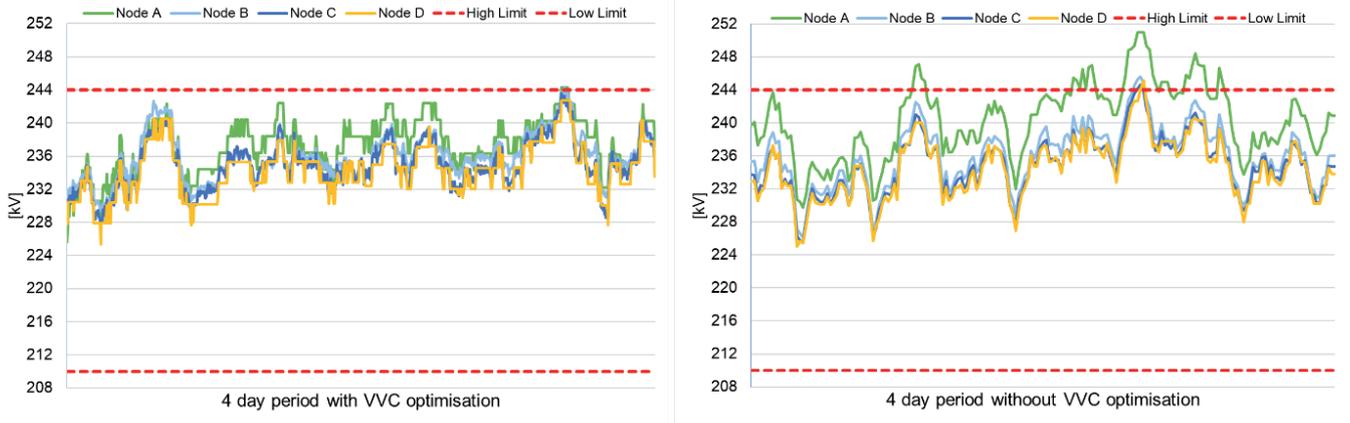


Fig. 2. Node voltages in 4-day period with optimization (the left side) and without optimization (the right side)

It can be clearly seen that during the VVC optimization cycles, node voltage magnitudes were all the time within defined limits, unlike the period when the VVC was not in the operation and the node voltage was outside defined limits. The VVC system keeps the node voltage magnitudes close to the high limit value, which is also a confirmation that the VVC performs a defined objective function to reduce MW losses. By increasing voltage level, the amount of current flow through network elements is consequently reduced, which leads to a consequent reduction of active power losses.

power losses by keeping voltages close to the high voltage limit, so during the testing, VVC raised node voltages in the system when that was feasible and consequently reduced the active power losses in the system.

Figure 3 shows a radar diagram of 220 kV and 400 kV node voltages in the power network before the implementation of VVC optimal setpoints and the same node voltages after the implementation of the VVC optimal setpoints. A heat map of network before and after the optimization cycle is also given for the same example in Figure 4.

As mentioned before, the VVC algorithm tries to reduce active

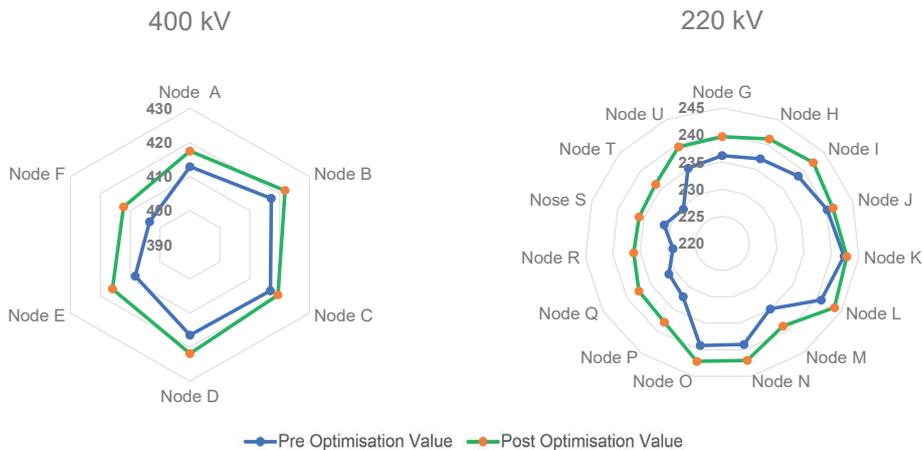


Fig. 3. Radar diagram of pre and post optimization voltages

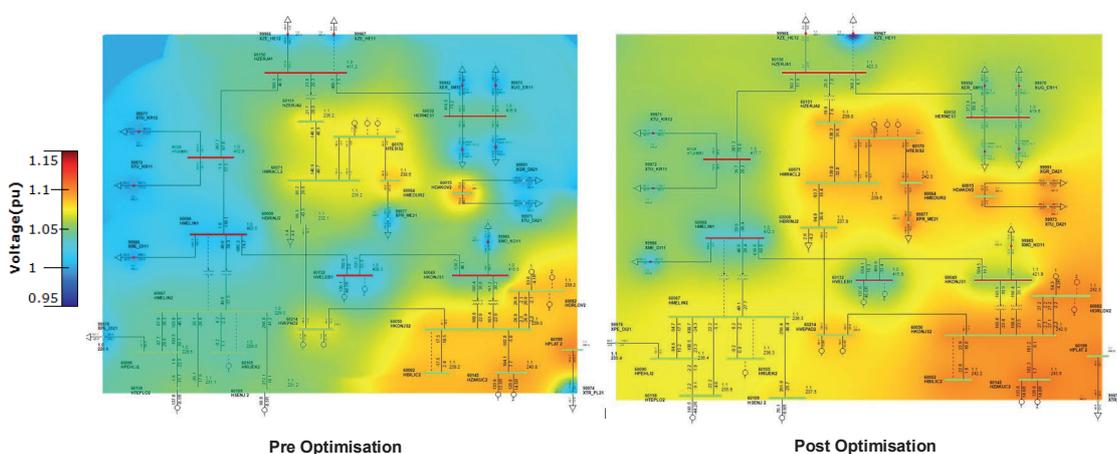


Fig. 4. The heat map of node voltages before and after performing the optimization

such as switching off or communication unavailability of the devices in the optimization or similar, VVC will immediately stop the execution in that region and prevent the possible occurrence of a dangerous situation in the network.

IV. SETTING UP OF THE OPTIMAL POWER SYSTEM STATE

The first step in implementing the VVC results is to switch off the local automatic control on individual objects in the optimization, i.e., to give the regulating control of individual objects to the VVC system. In the first run of the optimal power flow algorithm, a larger number of shifts in control variables occurs as a result the control variables now move in a coordinated manner to achieve the target function i.e., to reduce the operating losses in the system. Part of the test results is shown in Table III for two consecutive days of the field tests. The test started in the morning hours. The delta shift value shows the total number of shifts of tap changer position (transformers, VSR) from the initial value. The initial value in the first run of the VVC algorithm is the value inherited from the situation while the local (primary) control was active. Delta shifts for the following runs is the total number of shifts of tap changer position (17 transformers, 2 VSR) from the previous run. The number delta losses show the difference between the base case losses and the losses calculated after the execution of all controls. The losses are in each run reduced compared to the initial or previous value, but the most beneficial part is the equalization of the voltage profile and improving the overall voltage situation.

TABLE III
VVC SYSTEM FIELD TEST DATA

| VVC run | 1 st run | 2 nd run | 3 rd run | 4 th run | 5 th run | 6 th run | 7 th run | 8 th run | 9 th run |
|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| 1 st day | 10:42 | 11:42 | 12:42 | 13:42 | 14:42 | 15:42 | 16:44 | 17:51 | 18:42 |
| D shifts | 39 | 5 | 8 | 0 | 16 | 9 | 12 | 7 | 4 |
| D losses [MW] | -0.952 | -0.523 | -0.818 | -0.913 | -0.515 | -0.535 | -0.363 | -0.296 | -0.309 |
| 2 nd day | - | 11:37 | 12:40 | 13:42 | 15:13 | 16:37 | 17:54 | - | - |
| D shifts | - | 16 | 8 | 5 | 2 | 4 | 8 | - | - |
| D losses [MW] | - | -1.296 | -0.911 | -0.358 | -0.857 | -0.801 | -0.836 | - | - |

Although the goal of the OPF function is to minimize an objective function, in this case the power system active losses, the OPF function also must satisfy the power system physical and operational constraints. Satisfying the constraints, i.e., voltage constraints, takes precedence over achieving the highest degree of optimality. The objective function of minimizing losses acts in the opposite direction with the algorithm requirement to keep the node voltages in prescribed limits. Accordingly, the system losses after the VVC run might be higher than in the initial situation. This case usually coincides with the daily load profile. During the day, the power system is more loaded than in the evening or at night. Load changes that occur at night and in the morning are highly reflected in the change of voltage profile. Therefore, the VVC system during the day period did not propose major control variable shifts as in the night period or in the period of a sharp drop and increase in load. The changes in the control variables were logical, compensating for the change in voltage because of the change in load.

V. CHANGING OF CONTROL VARIABLES DURING VVC OPERATION

The voltage profile changes during the day and the change depends on the conditions in the network. Observing the voltage profile, correlation with the daily load profile can be noticed, i.e., in the reduced load period the voltage is higher, and in the period of increased load voltage is lower. This is a usual occurrence in the network. VVC in the optimization process tried to correct these changes in the voltage profile, i.e., in the specific periods of load change during the day a higher number of changes in control variables were made to successfully compensate the change of the voltage profile caused by load changes in the network.

For the purposes of the analysis, a graphical presentation was made in Figure 6 below. It contains the average number of changes in control variables per hour per day during a multiday VVC trial run. The number of changes in the control variables in this figure refers only to changes of transformers and variable shunt reactors tap changers.

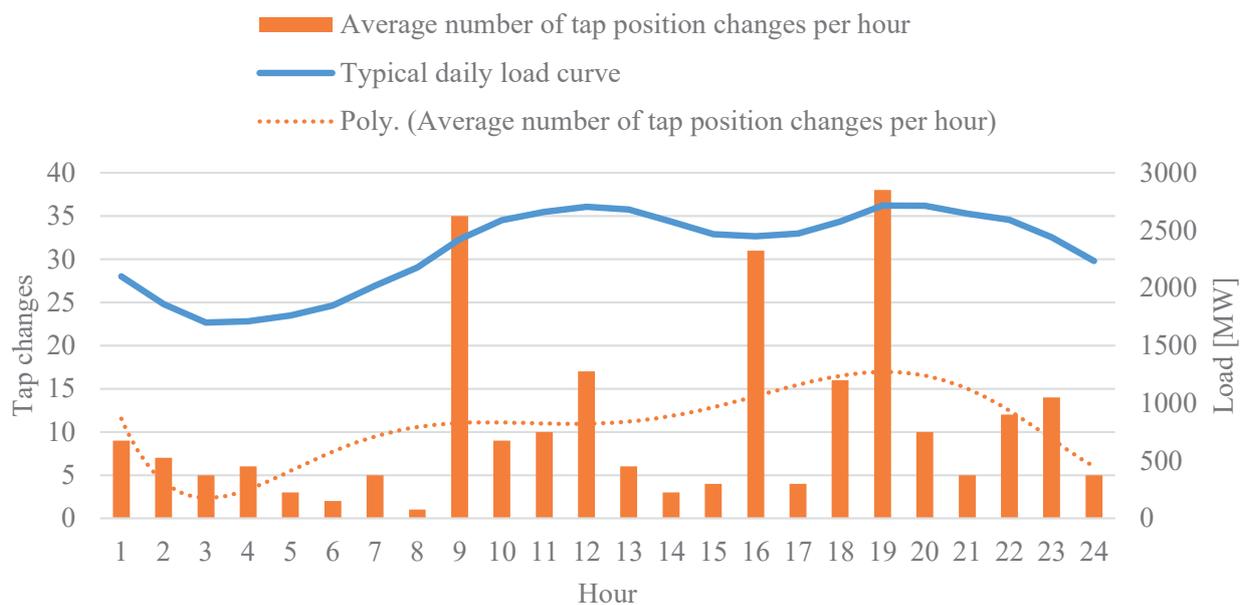


Fig. 6. Average number of control changes performed per hour and trend line of changes compared with daily load curve

Observing the graph above, higher number of changes in control variables are happening during the hours in which a significant change in load occurs. Also, a trend line of the change of control variables has been added, which clearly outlines the shape of the daily load diagram. This is one additional confirmation of how VVC successfully compensated the change in the voltage profile during the day and kept the voltage profile at the values most acceptable in terms of reducing active power losses in the system.

VI. CONCLUSION

The advantage of the VVC system implemented in HOPS is the possibility to operate the VVC in a closed loop without operator/dispatcher intervention. Due to its complexity, the closed loop approach of reactive power regulation is rarely used in the TSO community and HOPS is one of the first TSOs that implemented regulation in such manner. In conclusion, regardless of safety algorithms implemented to avoid many unwanted situations in the power system (such as voltage breakdown, overloading of regulating equipment and similar), transmission system operator should be aware of possible risks. For this reason, HOPS initially opted for safer approach and mostly used semi-automatic mode which is additionally under the control of the dispatcher/operator.

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